



Amphibionics : Build Your Own Biologically Inspired Reptilian Robot

Karl Williams

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This work provides the hobbyist with detailed mechanical, electronic, and PIC microcontroller knowledge needed to build and program a snake, frog, turtle, and alligator robots. It focuses on the construction of each robot in detail, and then explores the world of slithering, jumping, swimming, and walking robots, and the artificial intelligence needed with these platforms.

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